

Effect of Kurtosis-type of Primordial Non-Gaussianity on Halo Mass Function

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Utilize (1) void abundance (2) early star formation
(3) most massive object at high z , as a probe of
“non-skewed” non-Gaussianity

Kurtosis type non-Gaussianity

- Kurtosis: 4th order, non-Skewed

$$\zeta = \zeta_G + \frac{3}{5} f_{\text{NL}} (\zeta_G^2 - \langle \zeta_G^2 \rangle) + \frac{9}{25} g_{\text{NL}} \zeta_G^3$$

Trispectrum can be written as:

$$\langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \zeta(\mathbf{k}_3) \zeta(\mathbf{k}_4) \rangle = (2\pi)^3 T_\zeta(k_1, k_2, k_3, k_4) \delta^{(3)}(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3 + \mathbf{k}_4),$$

$$T_\zeta(k_1, k_2, k_3, k_4) = \tau_{\text{NL}} (P_\zeta(k_1) P_\zeta(k_2) P_\zeta(k_3) + 11 \text{perms.}) + \frac{54}{25} g_{\text{NL}} (P_\zeta(k_1) P_\zeta(k_2) P_\zeta(k_3) + 3 \text{perms.})$$

$$\tau_{\text{NL}} = \frac{36}{25} f_{\text{NL}}^2$$

This is true, only when primordial fluctuations are generated from a single scalar field.



For multi-field inflation, τ_{NL} is a parameter but with constraint:

$$\tau_{\text{NL}} \geq \frac{36}{25} f_{\text{NL}}^2$$

Unlike g_{NL} τ_{NL} has a lower bound.
Set a constraint on multi-field inflation.

T. Suyama and
M. Yamaguchi
2008

Kurtosis type non-Gaussianity

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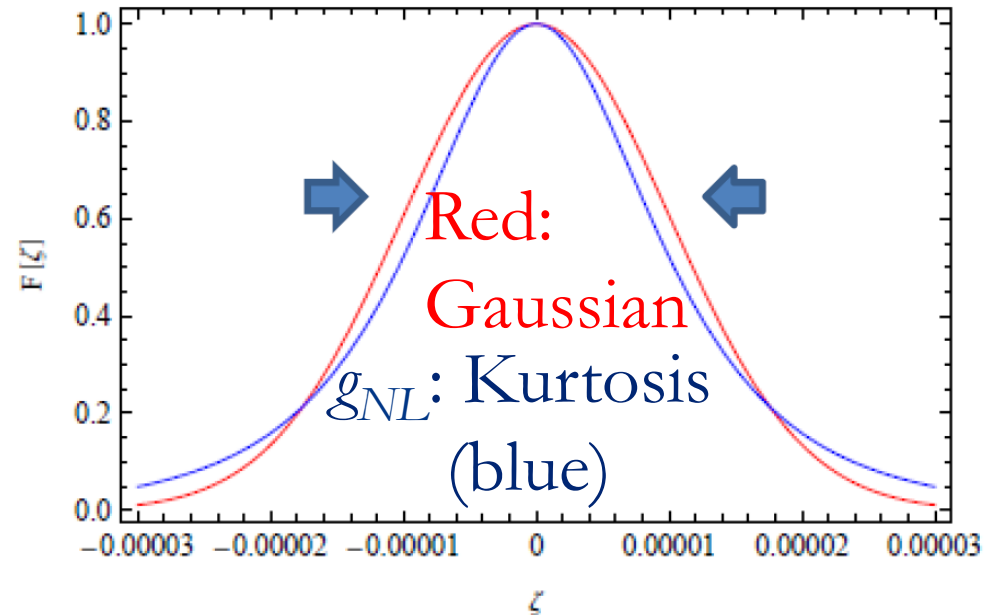
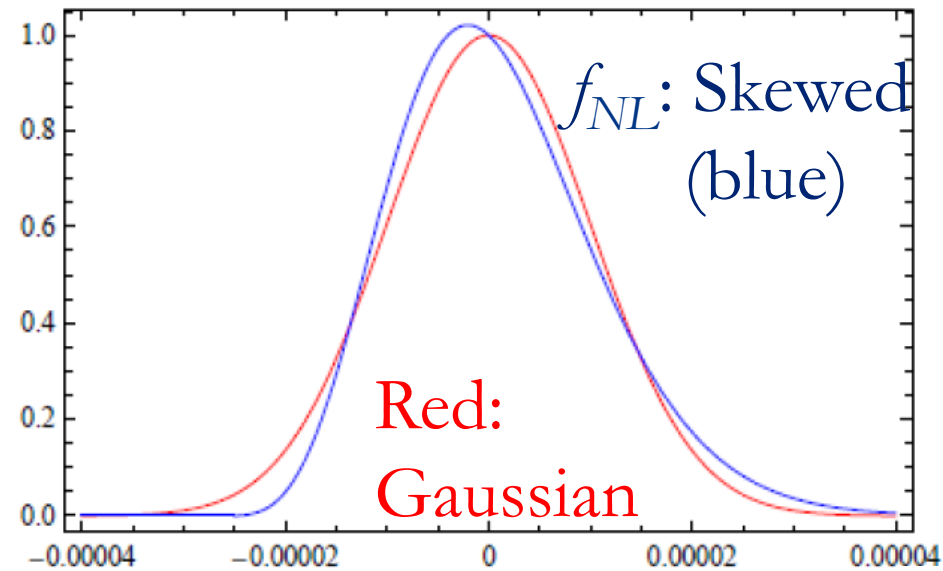


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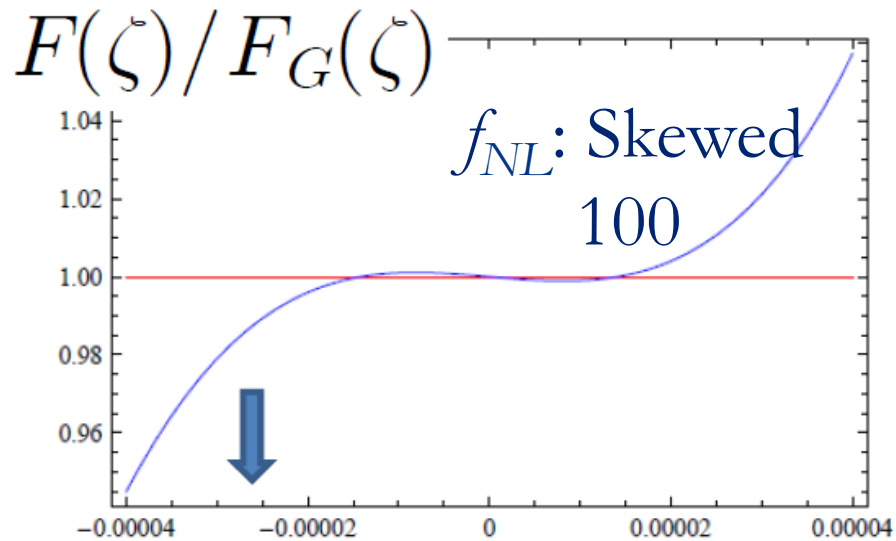
$$\tau_{\text{NL}} \geq \frac{36}{25} f_{\text{NL}}^2 / 2$$

Eiichiro's Talk

Probability Distribution Func.

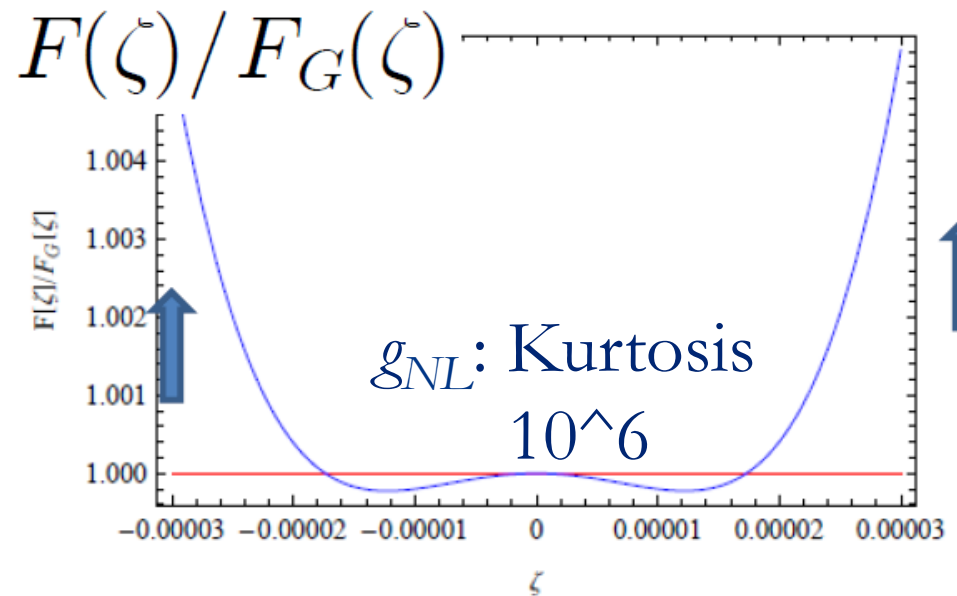


Probability Distribution Func.



Take the ratio
with Gaussian case

Huge Difference in the tails
Distinguishable?



Limits from WMAP

- $-10 < f_{\text{NL}} < 74$ (95%CL)

Komatsu et al. 2010

- $-7.4 \times 10^5 < g_{\text{NL}} < 8.2 \times 10^5$

- $-0.6 \times 10^4 < \tau_{\text{NL}} < 3.3 \times 10^4$

Smidt, Amblard, Byrnes, Cooray, Heavens, Munshi 2010

Here, in order to see the effect in the clear manner,
we take $\tau_{\text{NL}} = 10^6$

Non-Gaussian Mass Function

- Mass Function: Number of Collapsed Objects



Probability Density Function (PDF) is needed

$$\delta_R = \int \frac{d^3 \mathbf{k}}{(2\pi)^3} W_R(k) \delta(\mathbf{k}, z)$$

$$W_R(k) = 3 \left(\frac{\sin(kR)}{k^3 R^3} - \frac{\cos(kR)}{k^2 R^2} \right)$$



$F(\delta_R) d\delta_R$: PDF of δ_R

$$\langle \delta_R^n \rangle \equiv \int_{-\infty}^{\infty} \delta_R^n F(\delta_R) d\delta_R$$

n-th
central
moment

$$S_p(R) \equiv \frac{\langle \delta_R^p \rangle_c}{\langle \delta_R^2 \rangle_c^{p-1}}$$

p-th reduced
cumulant

S_3 : skewness

S_4 : kurtosis

$$\langle \delta_R \rangle_c = 0, \quad \langle \delta_R^2 \rangle_c = \langle \delta_R^2 \rangle \equiv \sigma_R^2,$$

$$\langle \delta_R^3 \rangle_c = \langle \delta_R^3 \rangle, \quad \langle \delta_R^4 \rangle_c = \langle \delta_R^4 \rangle - 3 \langle \delta_R^2 \rangle_c^2$$

Probability Distribution Func.

- Edgeworth expansion Juszkiewicz et al.95, LoVerde et al.08

$$F(\nu)d\nu = d\nu \left[c_0 F_G(\nu) + \sum_{m=1} \frac{c_m}{m!} (-1)^m H_m(\nu) F_G(\nu) \right]$$

$$F_G(\nu) \equiv (2\pi)^{-1/2} \exp(-\nu^2/2)$$

Coefficients can be evaluated:

$$c_0 = 1, c_1 = c_2 = 0, c_3 = -S_3(R)\sigma_R, c_4 = S_4(R)\sigma_R^2, \\ c_5 = -S_5(R)\sigma_R^3, c_6 = 10S_3(R)^2\sigma_R^2 + S_6(R)\sigma_R^4, \dots,$$

Non-Gaussian PDF can be obtained:

$$F(\nu)d\nu = \frac{d\nu}{\sqrt{2\pi}} \exp(-\nu^2/2) \left[1 + \frac{S_3(R)\sigma_R}{6} H_3(\nu) + \frac{1}{2} \left(\frac{S_3(R)\sigma_R}{6} \right)^2 H_6(\nu) + \frac{1}{6} \left(\frac{S_3(R)\sigma_R}{6} \right)^3 H_9(\nu) \right. \\ \left. + \frac{S_4(R)\sigma_R^2}{24} H_4(\nu) + \frac{1}{2} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^2 H_8(\nu) + \frac{1}{6} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^3 H_{12}(\nu) + \dots \right],$$

Halo Mass Function

$$\begin{aligned}
 \frac{dn}{dM}(M, z)dM &= -dM \frac{2\bar{\rho}}{M} \frac{d}{dM} \int_{\delta_c/\sigma_R}^{\infty} d\nu F(\nu) \\
 &= -dM \sqrt{\frac{2}{\pi}} \frac{\bar{\rho}}{M} \exp\left[-\frac{\nu_c^2}{2}\right] \left\{ \frac{d \ln \sigma_R}{dM} \nu_c \left[1 \right. \right. \\
 &\quad \left. \left. + \frac{S_3(R)\sigma_R}{6} H_3(\nu_c) + \frac{1}{2} \left(\frac{S_3(R)\sigma_R}{6} \right)^2 H_6(\nu_c) + \frac{1}{6} \left(\frac{S_3(R)\sigma_R}{6} \right)^3 H_9(\nu_c) \right. \right. \\
 &\quad \left. \left. + \frac{S_4(R)\sigma_R^2}{24} H_4(\nu_c) + \frac{1}{2} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^2 H_8(\nu_c) + \frac{1}{6} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^3 H_{12}(\nu_c) \right] \right. \\
 &\quad \left. + \frac{d}{dM} \left(\frac{S_3(R)\sigma_R}{6} \right) H_2(\nu_c) + \frac{1}{2} \frac{d}{dM} \left(\frac{S_3(R)\sigma_R}{6} \right)^2 H_5(\nu_c) + \frac{1}{6} \frac{d}{dM} \left(\frac{S_3(R)\sigma_R}{6} \right)^3 H_8(\nu_c) \right. \\
 &\quad \left. + \frac{d}{dM} \left(\frac{S_4(R)\sigma_R^2}{24} \right) H_3(\nu_c) + \frac{1}{2} \frac{d}{dM} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^2 H_7(\nu_c) + \frac{1}{6} \frac{d}{dM} \left(\frac{S_4(R)\sigma_R^2}{24} \right)^3 H_{11}(\nu_c) \right\} +
 \end{aligned}$$

NG term

Ratio to Gaussian Mass Function

$$R_{\text{NG}}(M, z) \equiv \frac{dn(M, z)/dM}{dn_{\text{G}}(M, z)/dM}$$

$$\frac{dn_{\text{G}}}{dM}(M, z)dM = -\sqrt{\frac{2}{\pi}} \frac{\bar{\rho}}{M} \exp\left[-\frac{\nu_c^2}{2}\right] \frac{d \ln \sigma_R}{dM} \nu_c dM$$

Fitting: Skewness & Kurtosis

In the squeezed limit (local type)

■ Skewness

$$\sigma_R S_3(R) = 4.3 \times 10^{-4} f_{\text{NL}} \times \sigma_R^{0.13} \quad (10^{12} h^{-1} M_\odot < M < 2 \times 10^{15} h^{-1} M_\odot)$$

De Simone, Maggiore & Riotto 2010; Enqvist, Hotchkiss & Taanila 2010

■ Kurtosis

from g_{NL}

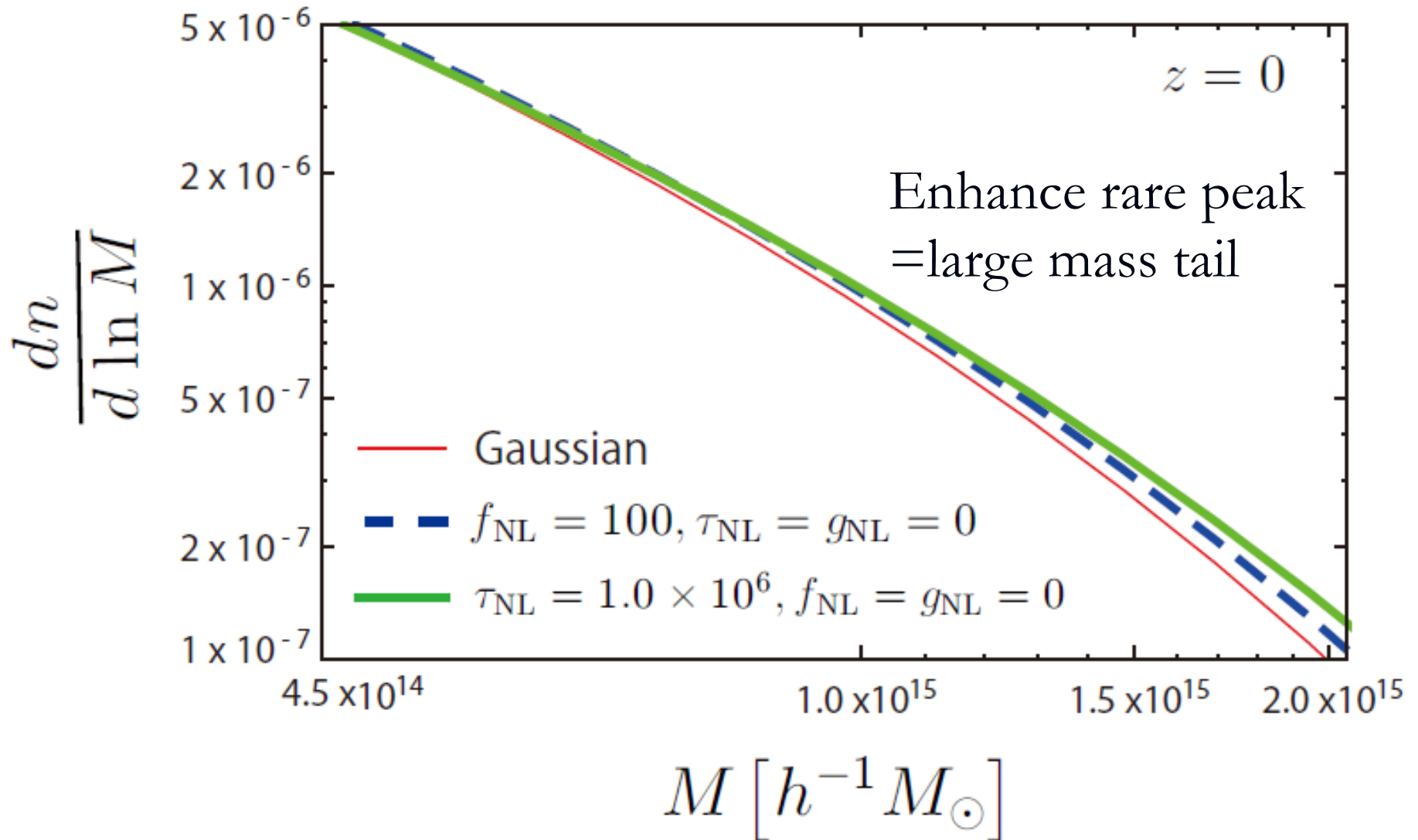
$$\sigma_R^2 S_4^g(R) = 9.4 \times 10^{-8} g_{\text{NL}} \times \sigma_R^{0.27} \quad (10^{12} h^{-1} M_\odot < M < 2 \times 10^{15} h^{-1} M_\odot)$$

Chongchitnan & Silk 2010a; Enqvist, Hotchkiss & Taanila 2010

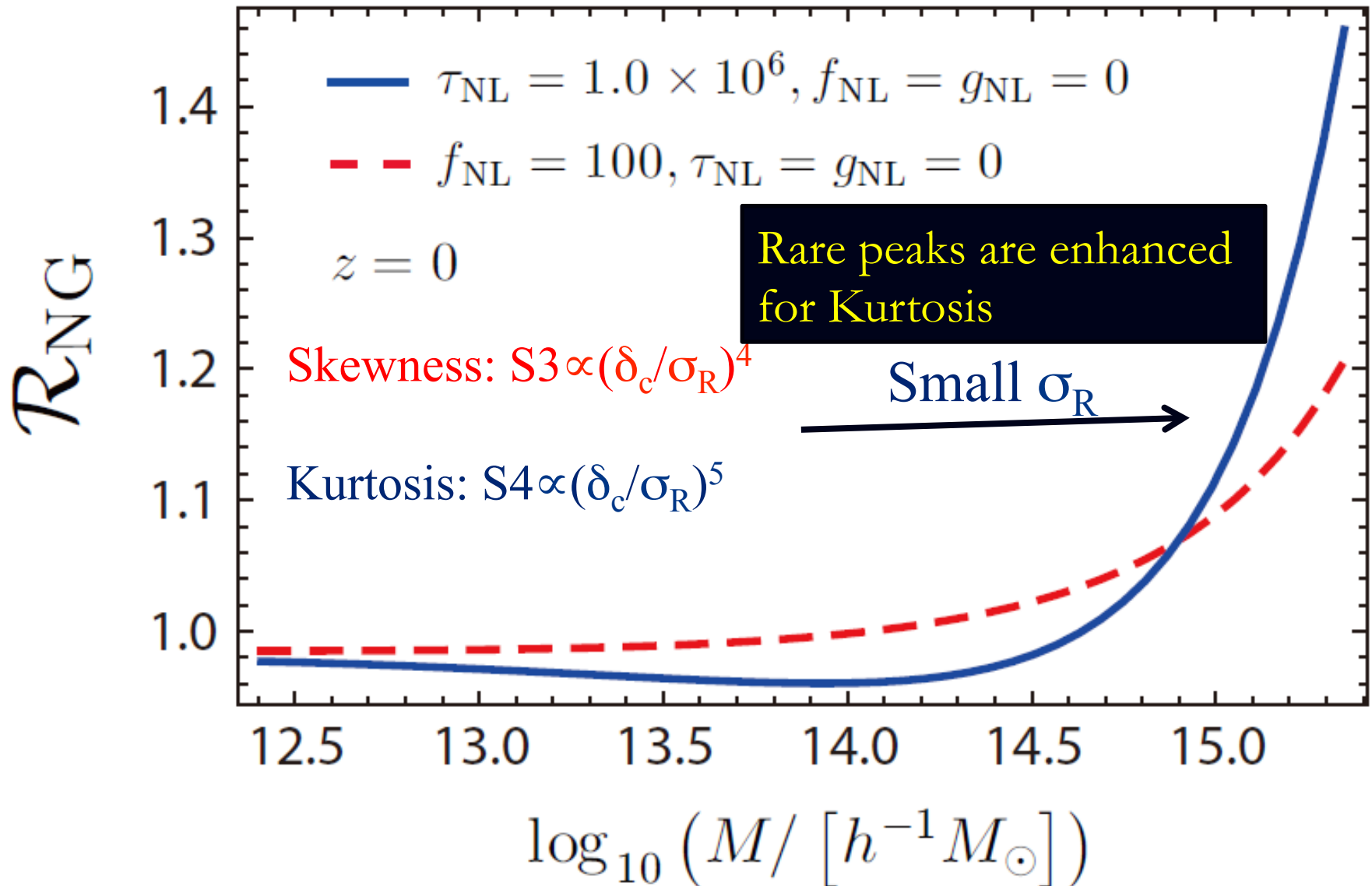
from τ_{NL}

$$\sigma_R^2 S_4^\tau(R) = 1.9 \times 10^{-7} \tau_{\text{NL}} \times \sigma_R^{0.25} \quad (10^{12} h^{-1} M_\odot < M < 2 \times 10^{15} h^{-1} M_\odot)$$

Mass Function



Mass Function (ratio to Gauss)



Application 1: Early Star Formation

- A simple analytic model
global star formation density

Somerville, et al. 2003

$$\dot{\rho}_* = e_* \rho_b \frac{d}{dt} F_h(M_{\text{vir}} > M > M_{\text{crit}}, t)$$

e_* : star formation efficiency: 0.001 – 0.002

M_{crit} : minimum collapsed mass: $10^6 h^{-1} M_{\text{SUN}}$

M_{vir} : virial mass $T_{\text{vir}} = 10^4 \text{K}$

F_b : fraction of the total mass in collapsed objects

$$F_h(M_{\text{vir}} > M > M_{\text{crit}}, z) = \frac{1}{\bar{\rho}} \int_{M_{\text{crit}}}^{M_{\text{vir}}} M \frac{dn}{dM}(M, z) dM \quad \leftarrow \text{NG}$$



$$\frac{dn_\gamma}{dt}(t) = e_* \rho_b N_\gamma (F_h(t) - F_h(t - \tau_{\text{III}}))$$

N_γ : # of photons/s/ M_{SUN}
 τ_{III} : life time of PopIII star

Application 1: Early Star Formation

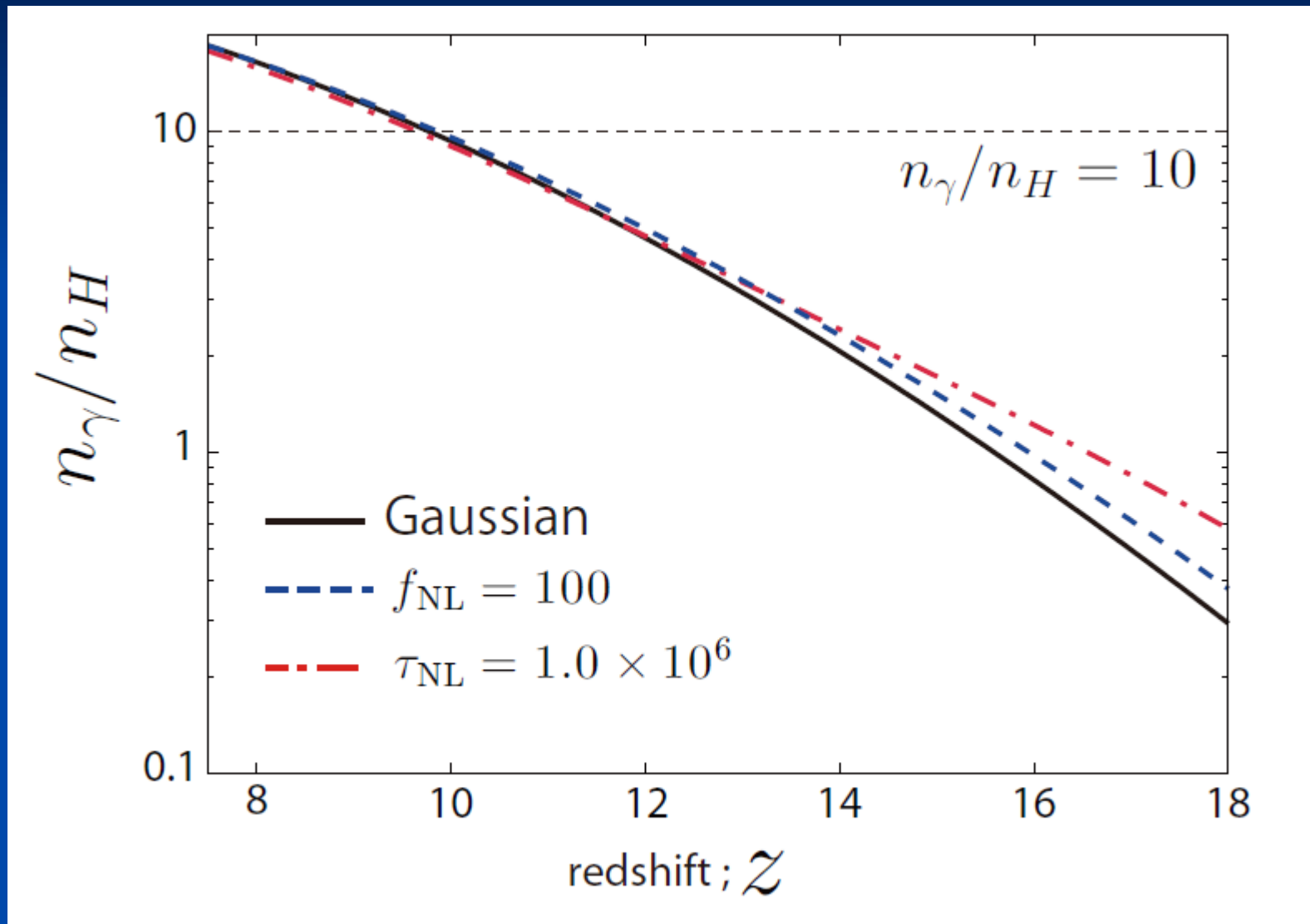
Cumulative # of ionizing photons/baryons

$$\frac{n_\gamma}{n_H}(z) \simeq \mu m_p e_* N_\gamma F_h(M_{\text{vir}} > M > M_{\text{crit}}, z) \tau_{\text{III}}$$

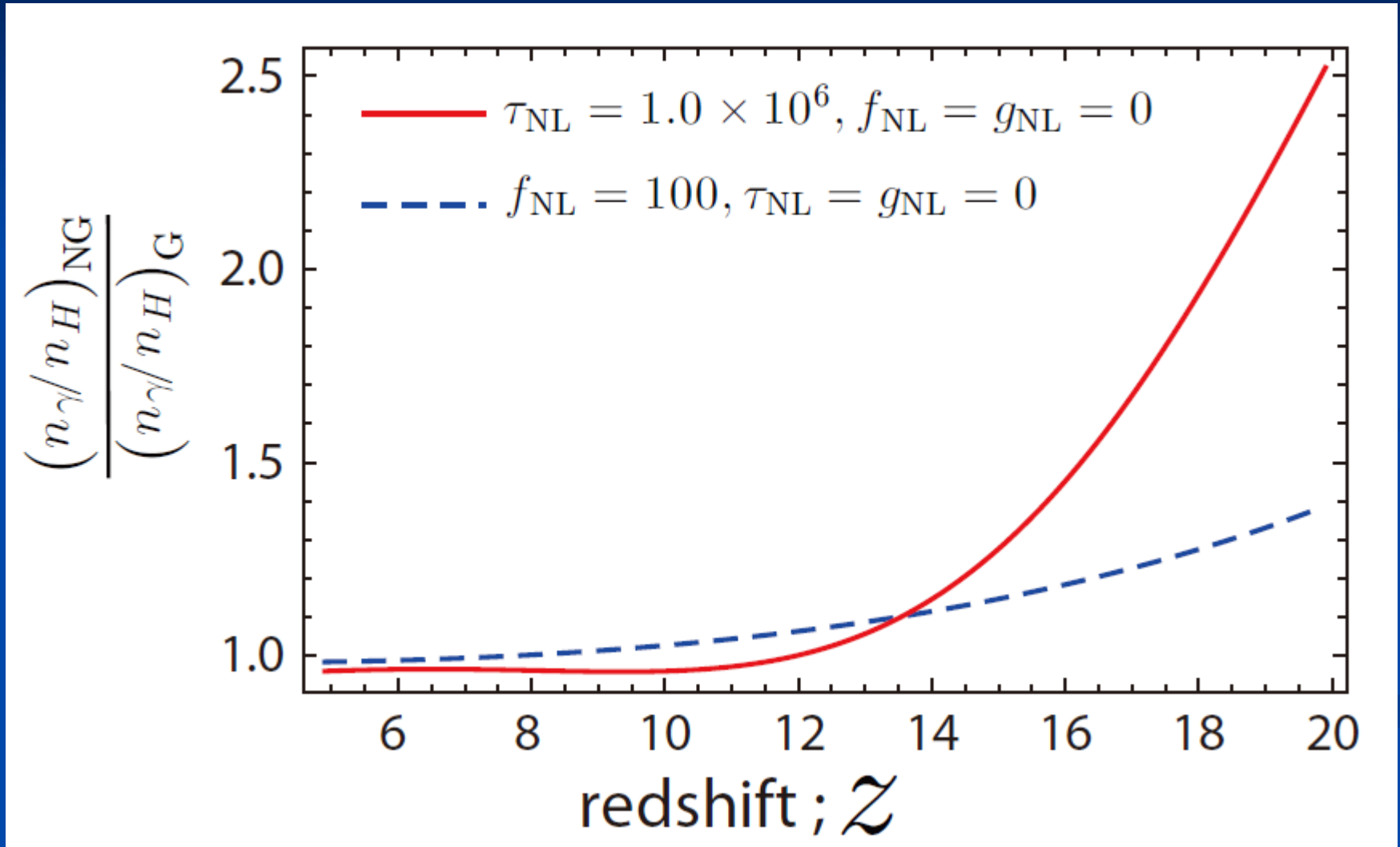
Good measure of reionization of inter galactic medium

Approx. $n_\gamma/n_H = 10$ is the epoch of reionization

Time evolution of Cumulative number of ionizing photons



Time evolution of Cumulative number of ionizing photons Non-Gaussian vs Gaussian



Application 1: Early Star Formation

- Non-Gaussianity doesn't affect much about global reionization history
- For the first star formation, however, non-Gaussian, especially Kurtosis type one enhances reionization a lot!

Application 2. High-Redshift Massive Clusters

- XMMU J2235.3-2557

at $z=1.4$, $M=(6.4\pm 1.2)\times 10^{14}M_{\text{SUN}}$

- Cayon et al. found to explain this, $f_{\text{NL}}=449$ is needed



Ruled out by WMAP constraints

This f_{NL} corresponds to $\tau_{\text{NL}}=1.7\times 10^6$
to obtain same R_{NG}

Application 3. Void Abundance

Press Schechter

Kamionkowski, Verde, Jimenez 2009

$$\frac{dn^{\text{void}}(R)}{dR} dR = -dR \times \frac{6}{4\pi R^3} \frac{d}{dR} \int_{-\infty}^{\delta_v/\sigma_R} F(\nu) d\nu$$

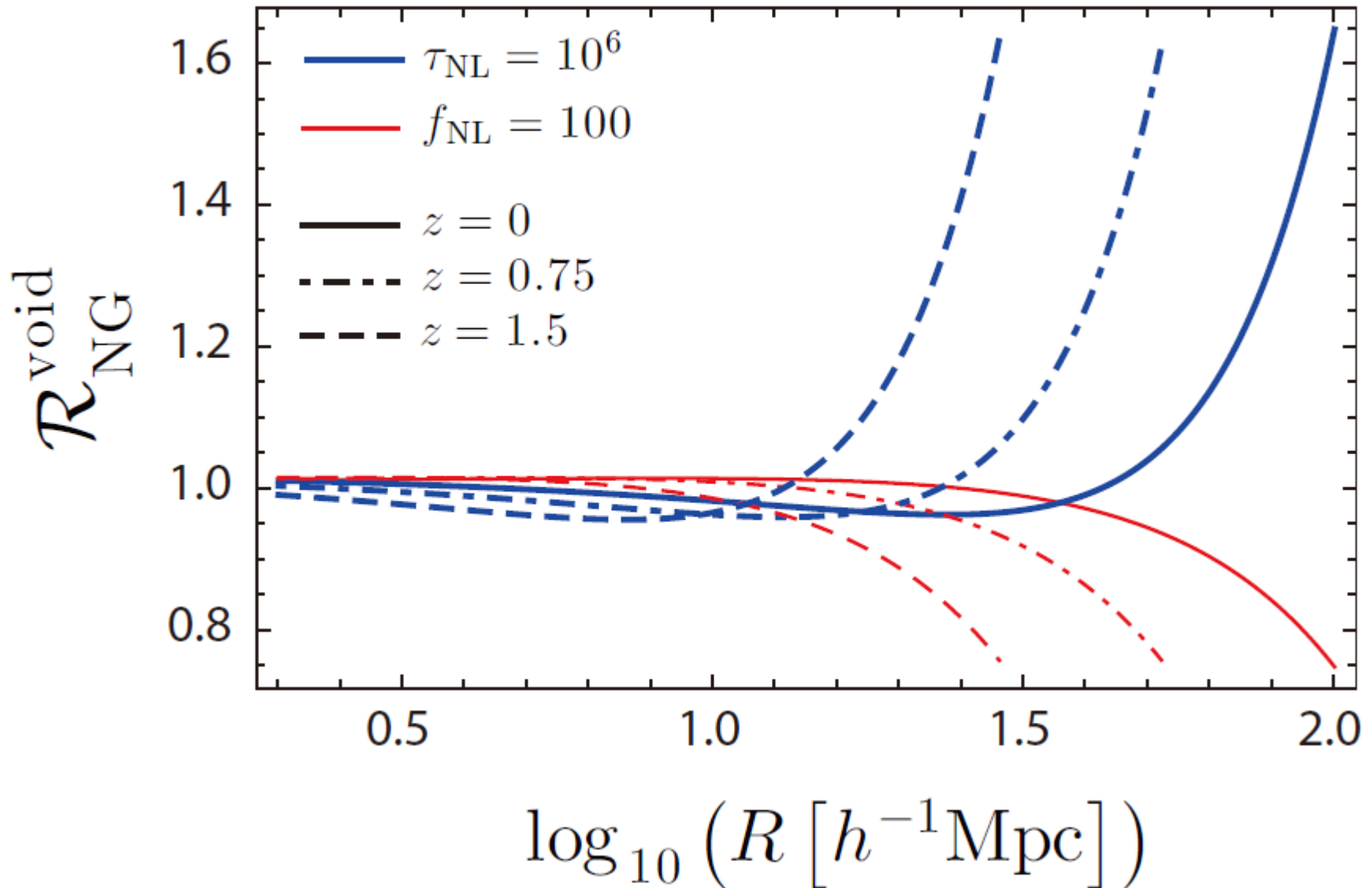
■ Gaussian

$$\frac{dn_G^{\text{void}}(R)}{dR} = \sqrt{\frac{2}{\pi}} \frac{3}{4\pi R^4} \exp\left[-\frac{\delta_v^2}{2\sigma_R^2}\right] \frac{\delta_v}{\sigma_R} \frac{d \ln \sigma_R}{d \ln R}$$

■ Non-Gaussian

$$\begin{aligned} \frac{dn^{\text{void}}(R)}{dR} = & \sqrt{\frac{2}{\pi}} \frac{3}{4\pi R^4} \exp\left[-\frac{\delta_v^2}{2\sigma_R^2}\right] \left\{ \frac{d \ln \sigma_R}{d \ln R} \frac{\delta_v}{\sigma_R} \left[1 \right. \right. \\ & \left. \left. + \frac{S_3(R)\sigma_R}{6} H_3(\delta_v/\sigma_R) + \frac{S_4(R)\sigma_R^2}{24} H_4(\delta_v/\sigma_R) \right] \right. \\ & \left. + \frac{d}{d \ln R} \left(\frac{S_3(R)\sigma_R}{6} \right) H_2(\delta_v/\sigma_R) + \frac{d}{d \ln R} \left(\frac{S_4(R)\sigma_R^2}{24} \right) H_3(\delta_v/\sigma_R) \right\} \end{aligned}$$

Void Abundance as a function of the size of void, R
Ratio between non-Gaussian and Gaussian cases



Application 3. Void Abundance

- Since it reflects the negative tail of the distribution function, τ_{NL} and f_{NL} work opposite directions
 - Positive τ_{NL} increases void abundance
 - Positive f_{NL} decreases void abundance



Combining Void abundance with other observations, e.g., massive cluster, early star formation, we can make a distinction between skewed and non-skewed non-Gaussian distribution

Summary

- We study the effect of the Kurtosis type primordial non-Gaussianity on structure formation.
 - obtain a formula of the halo mass function with primordial non-Gaussianities, including f_{NL} , g_{NL} , τ_{NL}
 - find the enhancement of the formation of the massive and high redshift objects, especially high density peak object for the Kurtosis type.
 - early phase of reionization of the Universe
 - massive clusters at high redshift
 - abundance of voids
- potential to distinguish skewness & kurtosis types

Another application of the mass function

Ionized bubble number count as a probe of non-Gaussianity

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²*Department of Physics and Astrophysics, Nagoya University, Chikusa, Nagoya 464-8602, Japan*

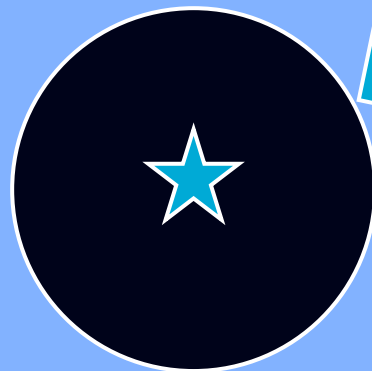
³*Institute for Physics and Mathematics of the Universe, University of Tokyo, 5-1-5 Kashiwa-no-Ha, Kashiwa, Chiba, 277-8582, Japan*

⁴*Kobayashi-Maskawa Institute for the Origin of Particles and the Universe, Nagoya University, I*

arXiv:1104.0139

- Utilize the number of Ionized bubbles at the epoch of reionization as a probe of non-Gaussianity

neutral



Ionized
bubble



Simple Analytic Model of Ionized Bubbles

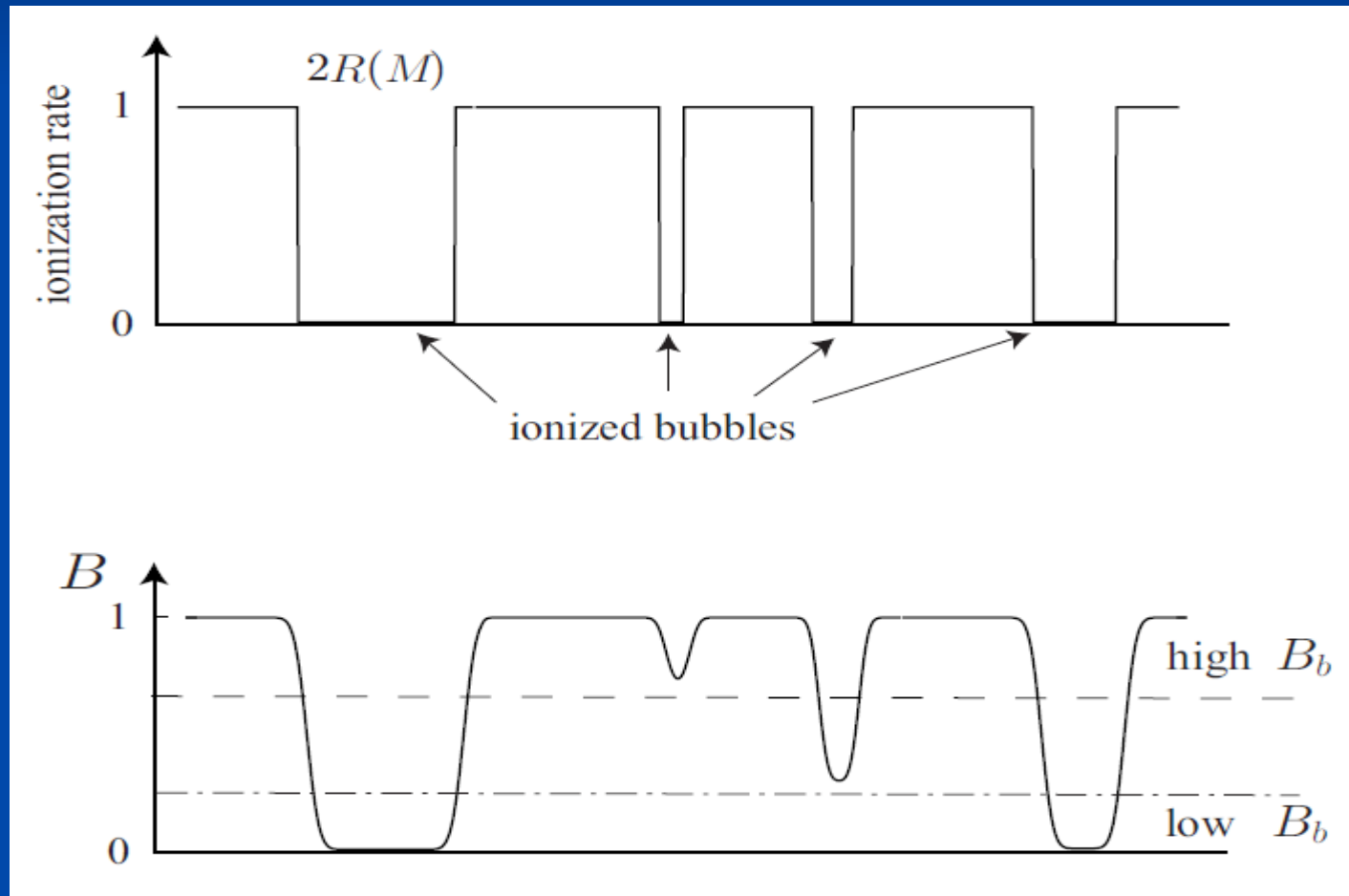
- Dark Halo whose virial temperature $>10^4\text{K}$ collapses, and forms spherical halo
- Size of ionized bubble (Loeb et al. 2005)

$$R_{\max} = 0.138 f_{\text{esc}}^{1/3} \left(\frac{M}{10^9 M_{\odot}} \right)^{1/3} \left(\frac{1+z}{11} \right)^{-1} \\ \times \left(\frac{\Omega_m h^2}{0.14} \right)^{-1/3} \left(\frac{N_{\gamma} f_*}{430} \right)^{1/3} \text{ Mpc}$$

- f_{esc} : escape fraction of photons, assumed to be 0.05
- N_{γ} : number of ionized photons per baryon in stars, 43,000 (Bromm et al . 2001)
- f_* : star formation efficiency, 0.05

Number Count of Ionized Bubbles

- Bubbles are detected as holes in 21cm map
- In actual observations, holes are smeared...



- Surface brightness temperature contrast of an ionized bubble (hole or not hole)

$$B(\theta, z) = \frac{Y_{obs}(\theta, z)}{T_{21}(z) \int d\Omega' \exp\left[-\frac{\theta'^2}{2\sigma^2}\right]}$$

- $\sigma = \theta_{FWHM}/\sqrt{8 \ln 2}$ Gaussian resolution
- $T_{21}(z)$: 21cm background temperature
- $Y_{obs}(\theta)$: surface brightness temperature

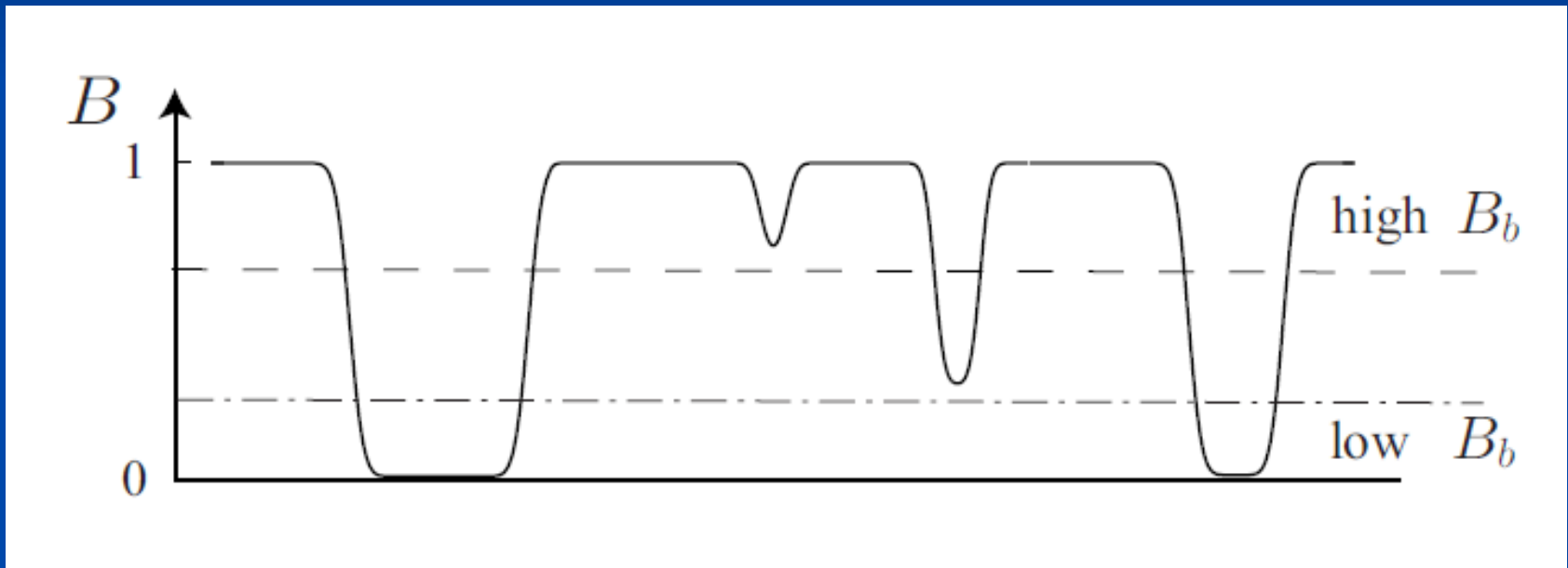
$$Y_{obs}(\theta, z) = \int d\Omega' T(\theta - \theta', z) \exp\left[-\frac{(\theta - \theta')^2}{2\sigma^2}\right]$$

- Angular profile $T(\theta, z)$

$$T(\theta, z) = \begin{cases} 0, & \theta < \theta_R \\ T_{21}(z), & \theta > \theta_R \end{cases}$$

Criterion of bubble detection

- Parameter B_b : assume bubbles with B smaller than B_b can be detected



- Number count of detectable bubbles

$$N(< B_b) = \int_{M_{\text{lim}}(B_b)} dM \frac{dV}{dz} \frac{dn}{dM} \Delta z$$

Possible observations

■ Angular resolution $\theta_{\text{FWHM}} = \lambda/D$

■ λ : frequency, $=21(1+z)\text{cm}$

■ D : baseline length

low resolution(LOFAR) 2km

high resolution(SKA) 5km

Density dispersion & Skewness

- Non-Gaussianity

$$\Phi(\mathbf{x}) = \Phi_G(\mathbf{x}) + f_{NL}(\Phi_G^2(\mathbf{x}) - \langle \Phi_G^2(\mathbf{x}) \rangle)$$

- Power spectrum $P(k)$

$$\langle \Phi_G(\mathbf{k})\Phi_G(\mathbf{k}') \rangle = (2\pi)^3 \delta_D(\mathbf{k} + \mathbf{k}') P(k)$$

- Smoothed density dispersion

$$\sigma_M^2(M) = \langle \delta_R^2 \rangle = \int \frac{dk^3}{(2\pi)^3} W(R, k)^2 D(k, z)^2 P(k)$$

- Smoothed Skewness

$$S_3(M) \equiv \frac{\langle \delta_R^3 \rangle}{\langle \delta_R^2 \rangle^2}$$

■ Here:

$$\begin{aligned} \langle \delta_R^3 \rangle &= \int \frac{d^3 k_1}{(2\pi)^3} \frac{d^3 k_2}{(2\pi)^3} \frac{d^3 k_3}{(2\pi)^3} W(R, k_1) W(R, k_2) W(R, k_3) \\ &\quad \times D(k_1, z) D(k_2, z) D(k_3, z) \langle \Phi(k_1) \Phi(k_2) \Phi(k_3) \rangle \end{aligned}$$

Mass Function

■ Mass Function

$$\frac{dn(M, z)}{dM} = -\sqrt{\frac{2}{\pi}} \frac{\bar{\rho}}{M} \exp\left[-\frac{\delta_c^2}{2\sigma_M^2}\right] \mathcal{R}_{NG}$$

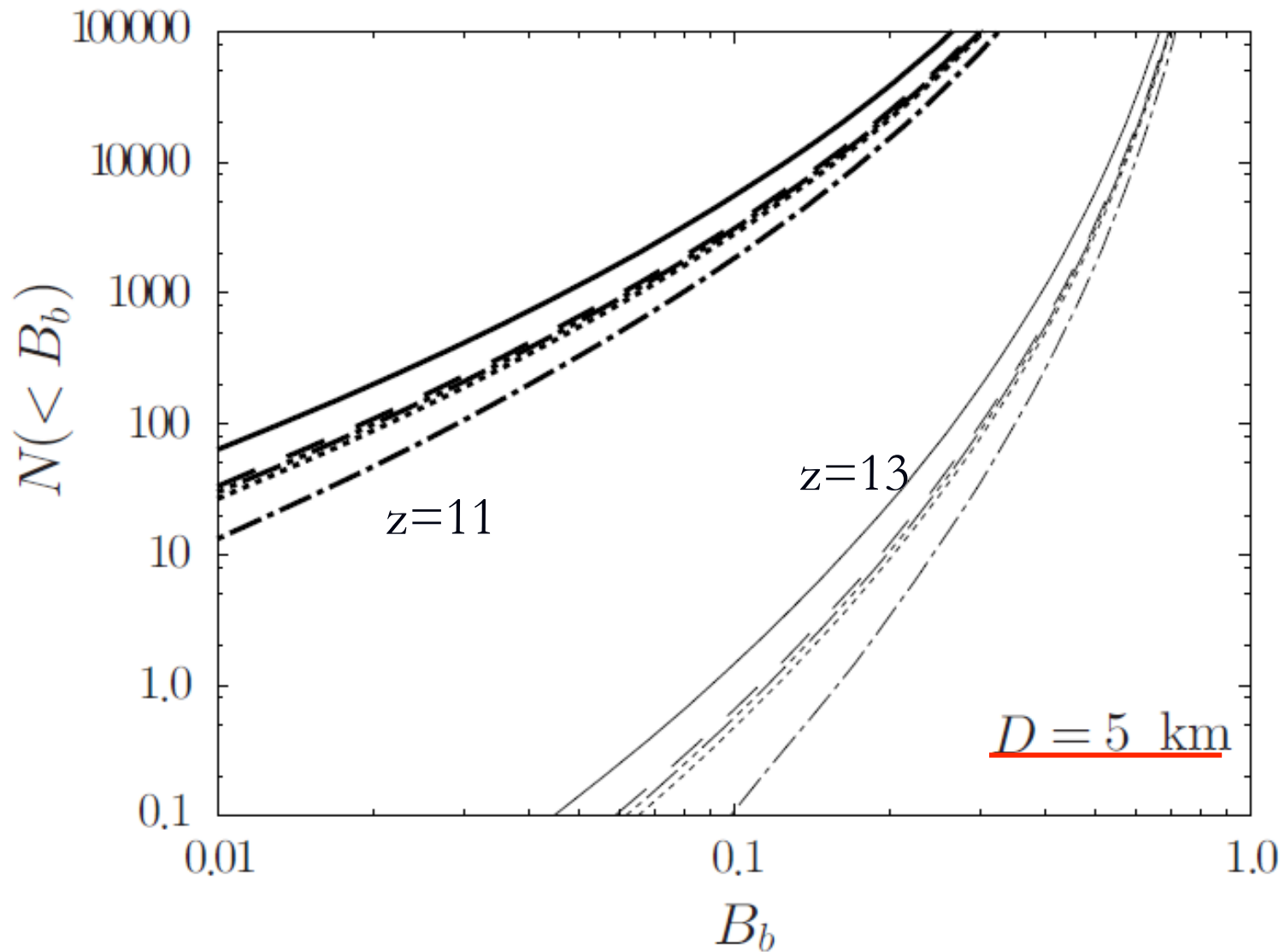
■ Here:

$$\mathcal{R}_{NG} = \left[\frac{d\ln\sigma_M}{dM} \left(\frac{\delta_c}{\sigma_M} + \frac{S_3\sigma_M}{6} \left(\frac{\delta_c^4}{\sigma_M^4} - 2\frac{\delta_c^2}{\sigma_M^2} - 1 \right) \right) + \frac{1}{6} \frac{dS_3}{dM} \sigma_M \left(\frac{\delta_c^2}{\sigma_M^2} - 1 \right) \right],$$



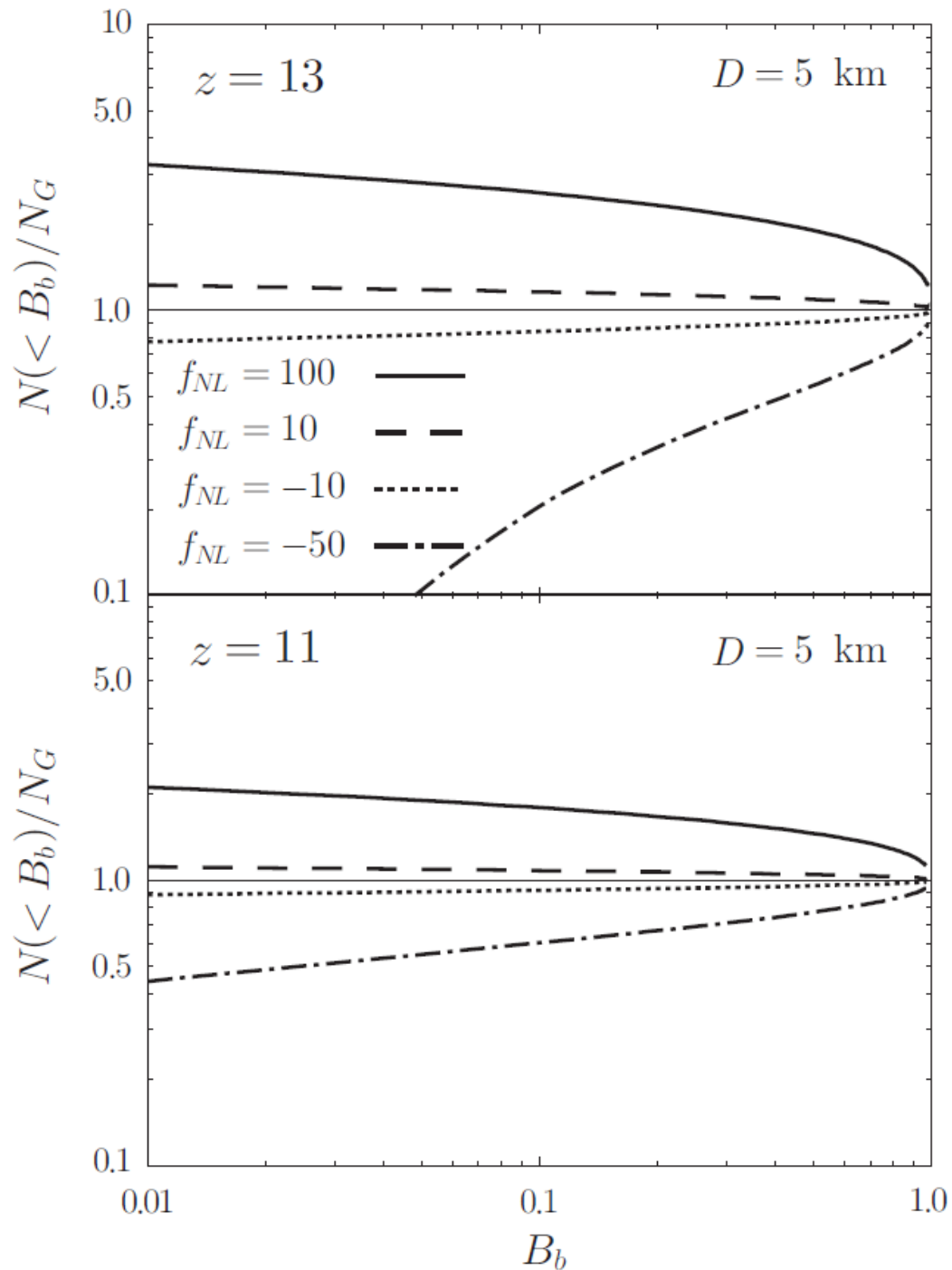
Non-Gaussian comes through S_3 terms

f_{NL} dependence of $N(<B_b)$



f_{NL} dependence of $\mathbf{N}(<B_b)$

- Large positive f_{NL} produces more number of bubbles from non-Gaussian tail
- At higher z
 - less number of bubbles produced for same B_b
 - smaller bubbles (large B_b)



Ratio to the Gaussian case

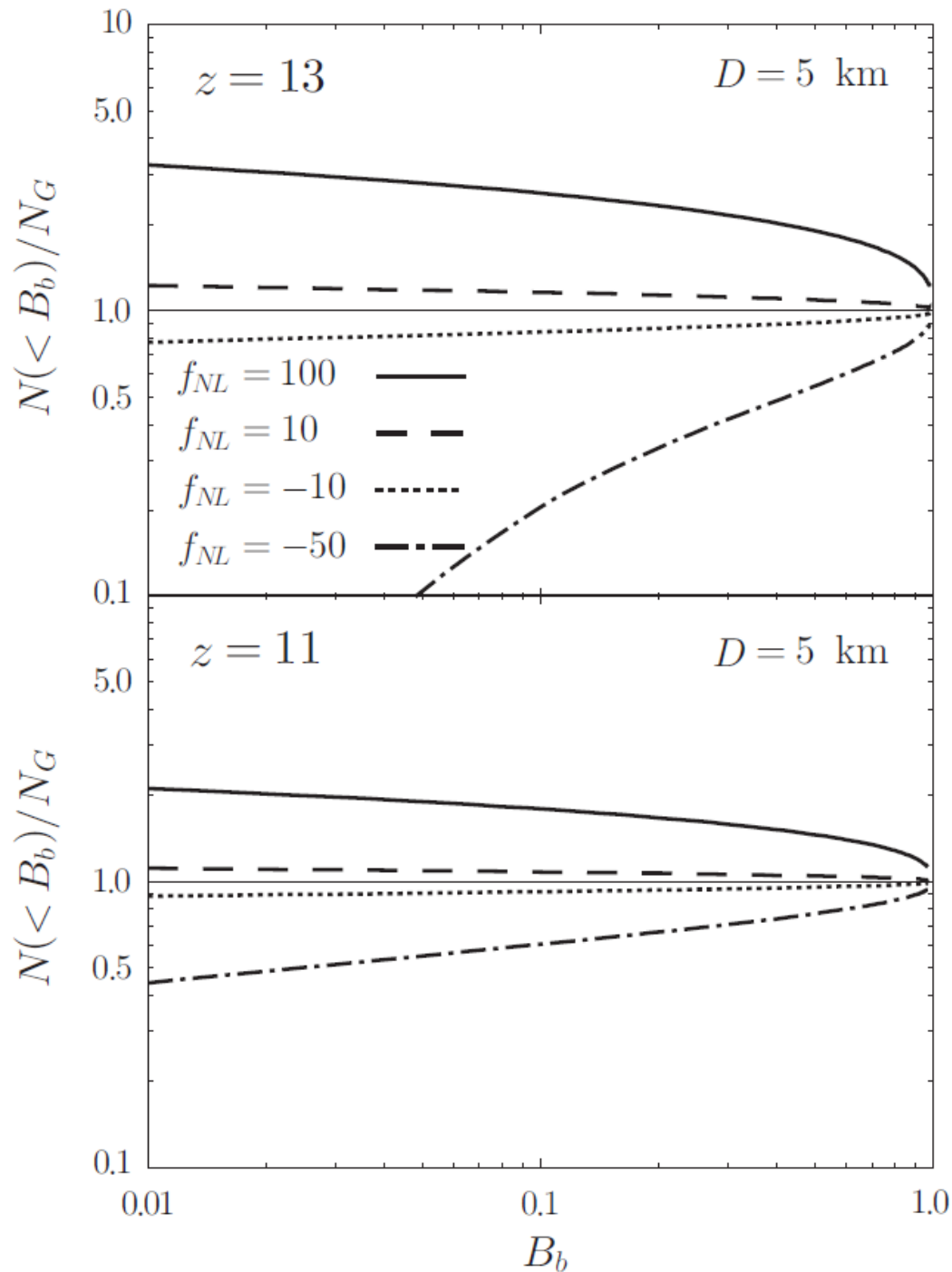
(1) Smaller bubbles
(larger B_b)



More numbers
(not rare objects)



Less significant
Non-Gaussianity



Ratio to the Gaussian case

(2) Higher redshift



Only rare objects
can be collapsed

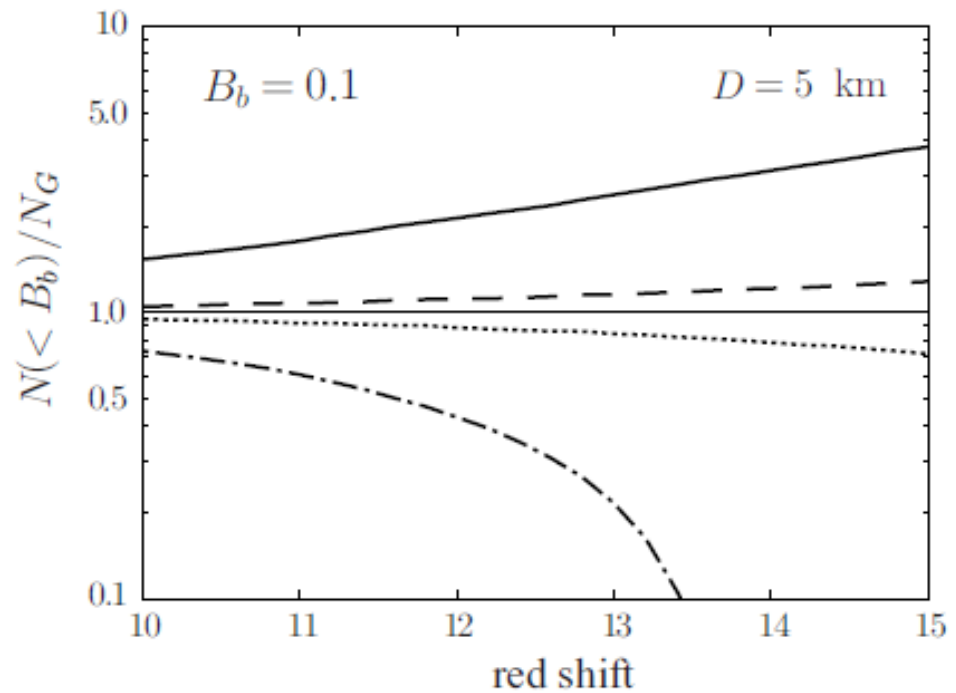
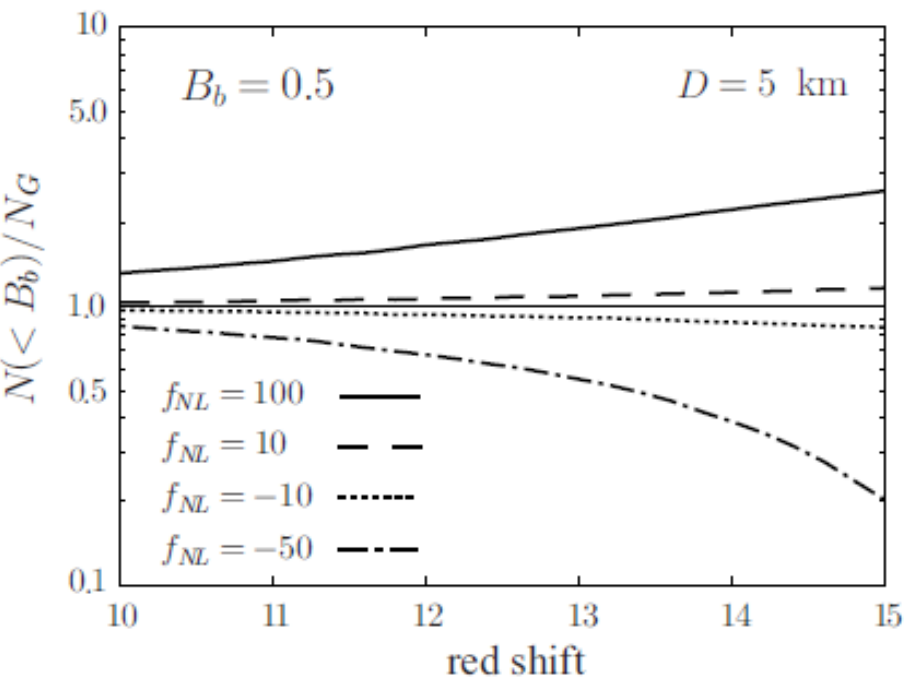


More significant
Non-Gaussianity

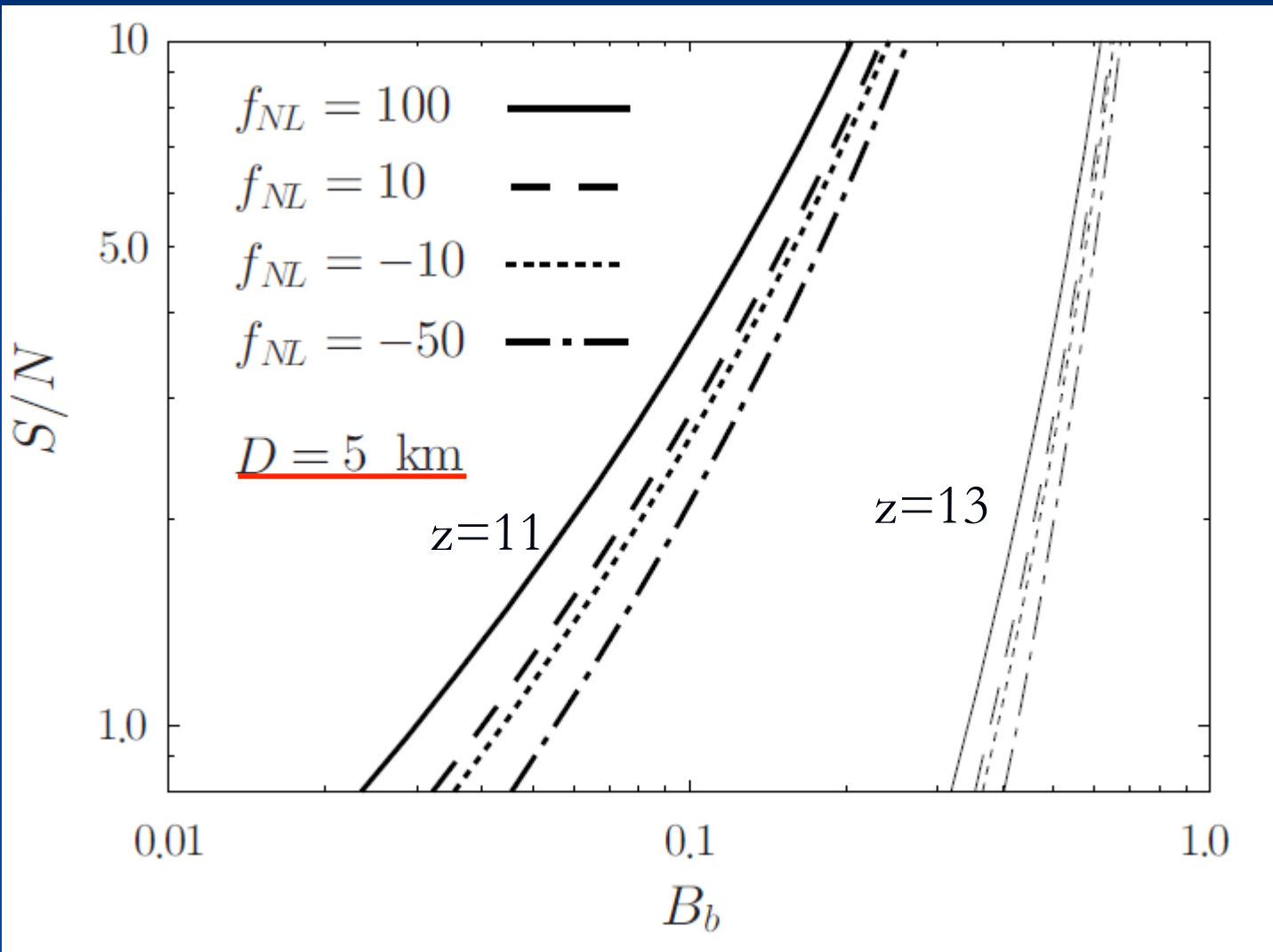
Time evolution of deviation from the Gaussian case

Small bubbles

Large bubbles



S/N: signal to noise ratio



Summary

of Bubbles can be a good measure of Non-Gaussianity

■ B_b

- Smaller $B_b \rightarrow$ larger deviation from Gaussian
- Smaller $B_b \rightarrow$ less number of Bubbles
- Optimal B_b for given S/N
 - S/N=10, $B_b = 0.2$ at $z=11$ ($N_{NG}(f_{NL}=100)/N_G \sim 1.7$)
 - S/N=3, $B_b = 0.1$ at $z=11$ ($N_{NG}(f_{NL}=100)/N_G \sim 1.9$)

■ z

- Higher $z \rightarrow$ larger deviation from Gaussian
- Higher $z \rightarrow$ Less number of bubbles
 - Ex) $B_b=0.1, z=13 \rightarrow N_{NG}(f_{NL}=100)/N_G \sim 2.5,$
BUT: $N_{NG}(f_{NL}=100) < 1$